

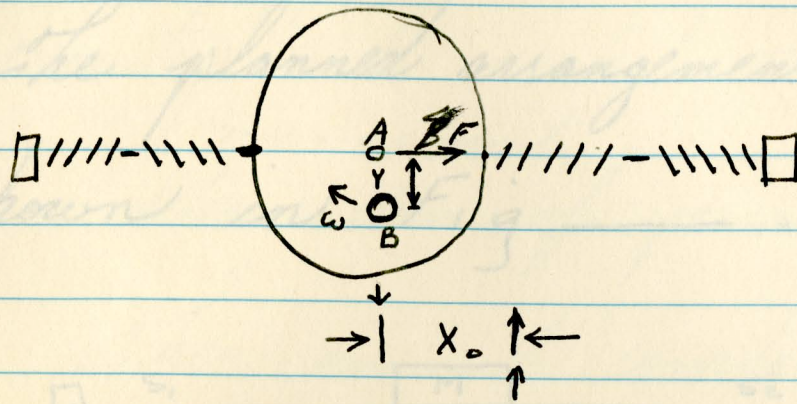
Mass Experiment
#3

7530-286-6951
FEDERAL SUPPLY SERVICE

16-74548-1 GPO

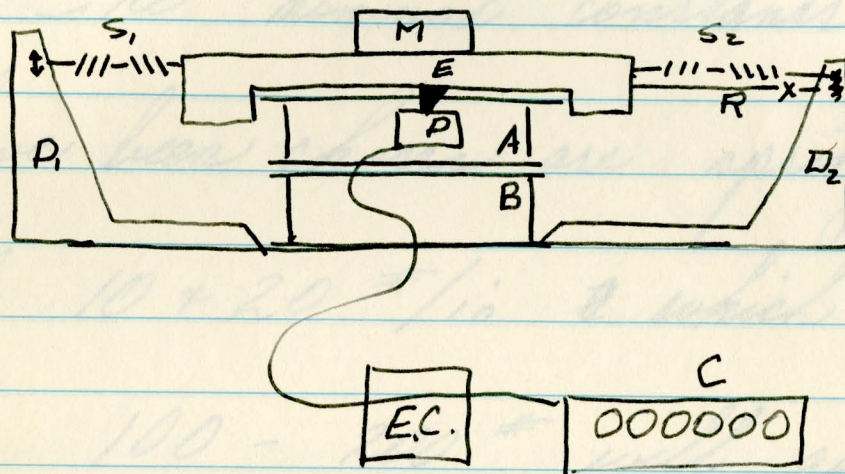
air bearing. ~~at~~ All of these
could be small units since the
forces will be correspondingly small.
In the interest of expediency
~~however~~ and in the absence of a
~~solution~~ theoretical solution to the
problem $\bar{z}$ 3 degrees of freedom,
restraints will not be initially
employed and the ~~error~~ magnitude
of motion in the undesired plane
and their effects upon accuracy will

be measured. It is obvious that ~~some~~ care will have to be taken in alignment of the springs and direction of release from initial displacement to ensure that these are coincident to the desired plane of measurement. It also seems probable that rotatory motion may be introduced if the center of mass is not in the axis of motion. This is



Shown in Fig - ~~One~~ After an initial displacement X_0 , at the moment of release a force $F = k X_0$ will be developed by the springs and if the mass is off center by AY a torque ω will be developed by $\bar{c}$ some rotational motion being produced.

The planned arrangement is shown in Fig —.



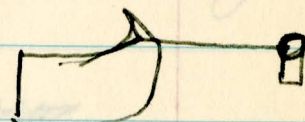
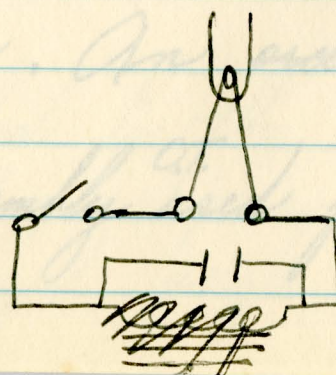
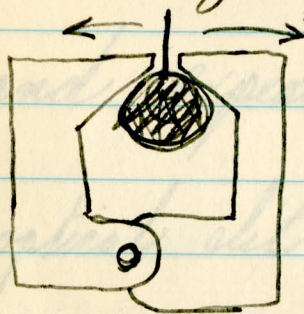
An adaptor E and D_{1-2} will be fabricated to allow attachment of the springs S_{1-2} , release mechanism R , & displacement pick off P to the existing bearing which will support a series of masses M . Electronic

circuitry ^{E.C.} will control the counter, ^{measurement} c
for determination of period.

The nominal constants which
have been chosen are spring rates
of $10 + 20 \text{ #/in}$ & which $\bar{c}$ masses
of $100 - 200 \text{ #}$ will give periods
of $\sim 1 - 3 \text{ secs.}$ Max. displacement
will be $\approx \pm 0.5''$.

The only requirements for the
adapter gear include rigidity such
that displacement under max. loads

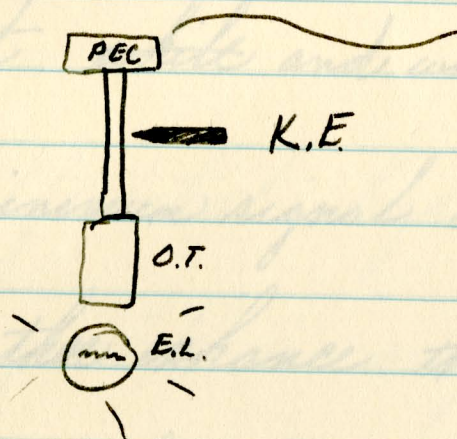
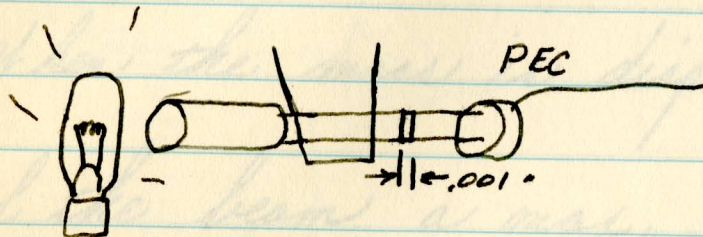
is $\ll 10^{-3}$ ins. - and for adjustment
to allow accurate alignment of the
spring forces $\bar{c}$ the axis of motion.
Considerable care will have to be
exercised in the release mechanism
to preclude movement in undesired axes.
This ~~not~~ could take the form
of a pair of jaws that ~~no~~ open
in exactly equally in opposite directions.



If extreme accuracy were desired
some form of exploding wire
arrangement as in Fig — 6
could be used.

It has been shown that
ultimate sensitivity will be a function
of the resolution of the zero
displacement detector. It is now planned
to use an optical scheme for accuracy
and expediency. An ordinary
optical slit assembly ^{O.T.} used for sound film

to the lamp E.L.
 reproduction will be used to provide
 a beam of light $\approx 10^{-3}$ in.
 wide which will fall on a
 light sensor, PEC. This assembly



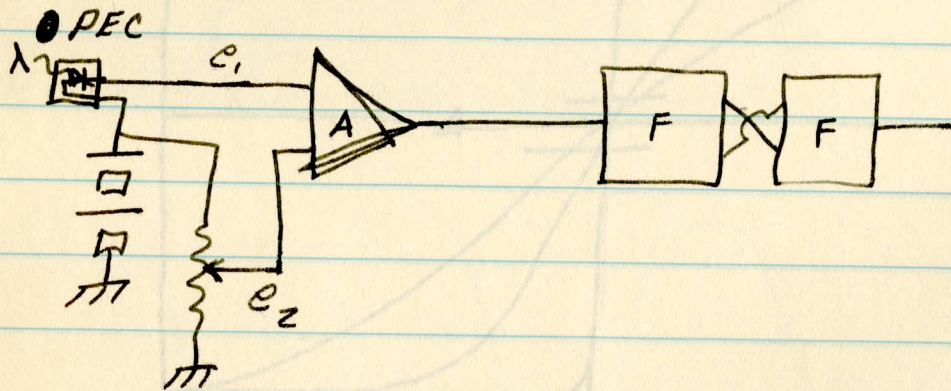
will be attached to the base to the
 the point of zero displacement, &
 beam at a right angle to the

direction of travel of ~~the~~ a
precisely ground knife edge (K.E.) attached
to the moving mass. This
~~will then provide a distance~~

When the mass is displaced right
of the beam a max. signal will
be present ~~while~~ and when displaced
left a minimum signal will be present -

To further enhance the distance resolution
especially in the face of possible
^(broadened)
~~defoc~~ crossing at a defocussed area
of the beam or a vertical skew

of the knife edge, an electrical mid point detector will be added as shown in Fig.

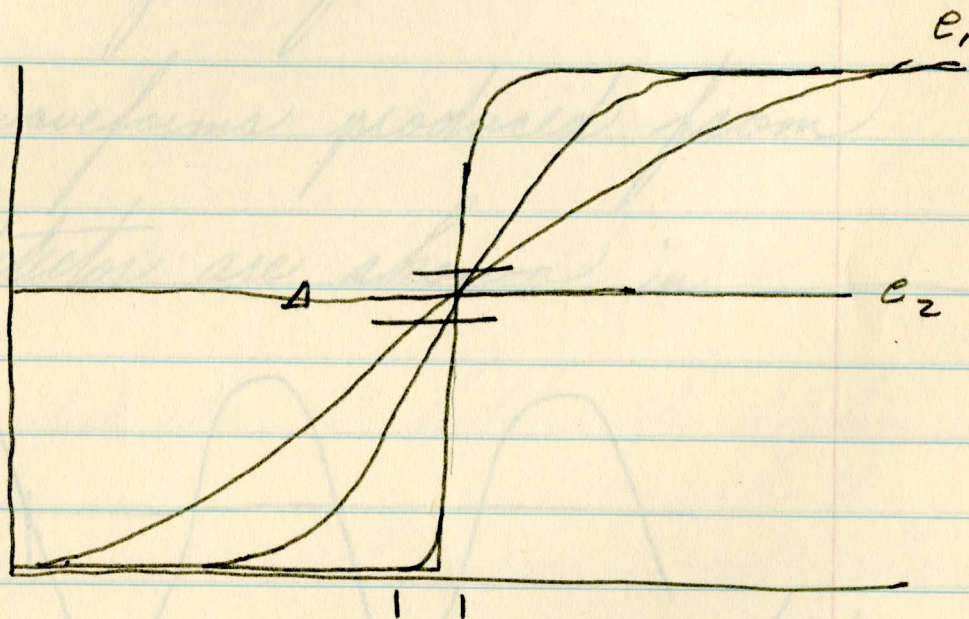


The differential high gain amplifier A will provide an output of $\sim 20V$ for a few mV difference in the signals e_1 & e_2 . e_2 will be set such that

it is $\frac{e_1}{2}$ of e_1 at max output-

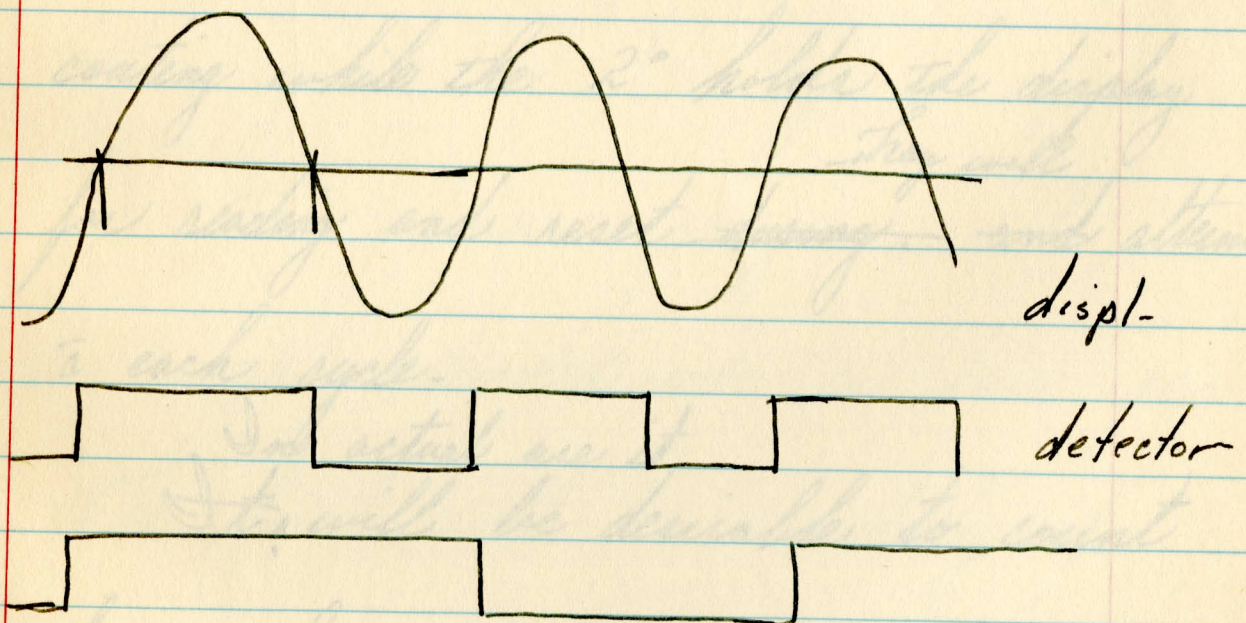
The resulting curves are shown in

Fig ———.



The net result is that zero
resolution
crossing is enhanced many fold and
accuracies of $< 10^{-3}$ should
be possible.

A second function of the electronic control is to provide a proper gate for the counter. The waveforms produced from the detector are shown in —



In order to convert these to full cycle an Eccles Jordan scale of two

will be used. Since it is desirable
to know the variations in each cycle
during the developmental phases, two
counters each $\bar{c}$ a time resolution of
 10^{-5} sec. will be used with one
counting while the 2^o holds the display
for reading and reset. ^{They will} ~~during~~ and alternating
 $\bar{c}$ each cycle.

In actual use it
It will be desirable to count
for the maximum possible number
of cycles since random variations

~~add~~ ^{summate} as $\sqrt{N}$ while the
measurements summate directly as N
for an increase in resolution ~~of~~
as $\sqrt{N}$. i.e. the random errors
would be reduced by $\frac{1}{2}$ by 4
~~some~~ cycles or $\frac{1}{3}$ by 9 cycles.

The planned program will
be roughly divided into two phases.
The first will be a study of
errors & variations involved ~~using~~
in the method & particular instrument.
~~It~~ + During this phase it may

be necessary to add a 2nd
~~rest~~ bearing system or make
other changes. The 2nd phase
will consist of measurements of
man and the development of whatever
~~technique~~ additional techniques are
required -

Assuming that the method
proves practical, and there appears
to be no reason why it will not
at this time, ~~one~~ there remains the
problem of use under actual

conditions. This will be easier in several ways. ~~Large~~ support bearings capable of supporting heavy loads will not be required. A single pair of ~~two~~ cylindrical bearings as shown in _____ using requiring only 1-2

P.S.I. will be required. ~~Drag~~ friction will be ^{further} reduced. One possible arrangement is shown in

_____ - A chair, which could be used in normal duties will be provided
a foot & hand holds for the

muscular ~~soft~~ rigidity to be developed.

In normal use it would be
latched to ~~the~~^{its} frame while for weighing
it would be unlatched and free to
move along the axis provided by the
air for the bearing could simply be bled from the
vertical air bearings. This unlatching
ships circulating air system.
would also ~~ension~~ apply tension
to a set of springs which would
then ~~displace the man~~ hold the
man at ~~now~~ some neutral position
until a small ~~step~~ ~~to~~ initial

displacement caused oscillation about this point. A simplified optical or other zero pickoff system would then provide a signal to a counter. The counter might well be part of other equipment - In any event ~~the~~ ^a ~~my~~ major portion of the counter, an accurate time base, will certainly be on board & suitable for use. This ~~is~~ seat scale could be absolutely calibrated in free fall prior to launch or else $\bar{c}$ known masses

on board the ship after launch.

A single scale will obviously not cover the entire range accurately and smaller versions in other configurations of this arrangement could be made for measurements that are bound to occur $\bar{c}$ man in space -