

Construction & Operation  
of  
Mod 2B Radar Optic  
FEI

Developed by  
W<sup>m</sup> Thornton

mm

This F.C.D. system was ~~designed~~  
designed and developed at A.O.G.C.  
as a unit which ~~is~~ could be built,  
~~operated and~~  
~~maintained by field & operational~~  
units with suitable shop facilities.

It is a new and simplified design  
of ~~sadar optic~~  
of a scoring system developed here.

~~It works~~ A prototype was built  
and ~~first~~ operated ~~to~~ to run down  
as many bugs as possible as well as  
to determine operating procedures. Ideas to  
further simplify this unit have been  
constantly appearing up ~~to~~ <sup>from</sup> the time of  
of writing and they will undoubtedly  
continue to do so. The unit appears to  
be relatively bug free however for the  
total maintenance ~~to~~ during some 12 or

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15 missions has been the replacement  
of 1 fuse which was underated.  
All items used <sup>except one</sup> are stock and are  
listed. The one exception is a camera  
<sup>suitable</sup> since the Air Force has no decent ~~is~~ motor  
driven 35 mm camera available. The  
camera used is a Model 4 C mfg  
and sold by Flight Research Corp.,  
Richmond Va. This camera is almost  
ideal for the job and little difficulty should  
be experienced <sup>in</sup> obtaining them. Any motor  
driven 35 mm camera with frame  
rates of 20 to 50 per second would  
be suitable with slight modifications to  
the <sup>A scope</sup> combining system. At present work  
is under way <sup>here</sup> in the Photo Optic

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Lab to fit the A-7 to this installation.

Theory of operation of this form  
method of scoring ~~miss~~, simplified, runs  
as follows. A motion picture record is  
made of ~~the~~ rocket's path past the target  
by a camera in a chase plane flying through  
a firing run in formation with ~~the~~ firing  
aircraft. Concurrently with ~~the~~ strike  
camera record a record is made of a  
radar A scope presentation on which  
is displayed both rockets and targets ~~to~~  
from relative range. When the range of  
pattern centroid is coincident with target  
range ~~the~~ corresponding photograph is  
taken from the strike record. Miss  
distance is obtained from this frame  
of film by comparing miss distance

of centroid to target length.

In this ~~Mod. 26 second~~ F.E.I. functions of strike camera and scope camera are combined to eliminate difficulties of synchronizing cameras, assessment problems and others. A modified 4" Balter lens is removed from its lens barrel and screwed into ~~the~~ an ~~adapter~~ ~~base~~

Drawings # 4 + 7 ~~These~~ lens are focussed individually at the factory so it will ~~not~~ be necessary to refocus them on the modified barrel by screwing ~~the~~ lens proper onto ~~the~~ <sup>modified</sup> barrel in ~~the~~ correct position and pinning it there. This can be accomplished on an optical bench or more simply on a camera with a <sup>bore sight</sup> bore sight tool. The 4" lens images ~~the~~ strike information on the film while a 2" lens set in the adapter images through

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~~Drawing 4+5~~

a mirror onto one edge of frame aperture  
A scope information. In order to place  
this cathode ray tube in a practical practical  
position it was necessary to use a  
mirror mounted on the camera (Drawing 4+5)

~~This lens leaves something to be desired in  
speed as it is only f 4.5 max and for  
this reason the shutter opening on this <sup>image</sup> portion  
of ~~the~~ is increased (Drawing. 8 )~~

It is absolutely mandatory to use a  
3JP11 tube for the much higher actinic  
value of its phosphor. At these writing speeds  
light from a green phosphor P-1 will not  
produce an acceptable trace. Class D film  
also <sup>speed</sup> is used to gain a slight advantage.

See drawing ~~(4+6)~~ for mounting  
detail of cathode ~~ray~~ ray tube. Power for  
this tube is from a high voltage supply used  
in pilot's presentation of T-36-D. F94 C

To ~~not~~ provide necessary voltages for an 'A' presentation on the 35P-11 a sweep and video circuit simple to the point of crudity is used. It ~~fit~~ is entirely adequate however. ~~The~~ All power plus trigger and video pulses are obtained from a G-30. This unit is constructed on an aluminum chassis which fits the same type shock mount as ~~the~~ voltage regulator of the G-30. Video amplifier is a straight R.C. coupled pentode receiving video information from the video jacks on range computer and power supply. ~~R<sub>20</sub>~~ R<sub>20</sub> is kept <sup>low</sup> small to maintain time rise of ~~the~~ pulses. It first appeared that some form of peaking network would be ~~neces~~ necessary to keep ~~the~~ out put ext fast enough and yet with a reasonable gain however this was

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not necessary if all leads are kept short and good high frequency practice is followed in construction.

A negative <sup>trigger</sup> pulse from the no from the G-30 R.F. unit initiates sweep and unblanking functions. <sup>Drawing 14 & 15</sup> This trigger is coupled thru a diode  $V_1^*$  to the normally non-conducting plate of a univibrator. The current is drawn by this trigger causing ~~no~~ conduction in this ~~two~~ triode while the other is cut off. This state remains until enough charge has leaked off  $C_3$  and  $C_4$  for the circuit to return to its normal state. Output of this circuit is a large negative pulse which may be varied in duration from ~~one~~ to 3 to 15 micro seconds.

This negative pulse gates the sweep and intensifier ~~alt~~ circuits through  $C_5$  and  $R_9$ . \* This tube has later been replaced by two IN34A diodes in series.

To keep screen burning and other undesirable effects down, ~~the beam of cathode ray~~  
 tube beam is turned on only during sweeps.  
 A negative gate is applied to  $\frac{1}{2}$  of  
 $V_3$  which is conducting heavily causing  
 the tube to cut off ~~Diagram 14-16~~. An almost square  
 pulse is then applied to the grid of  $V_6$  (3IP11)  
~~turning~~ allowing beam current to flow for pulse  
 duration.

To generate necessary sawtooth voltages  
 for sweeps a negative gate is applied to  
 clamp tube  $V_3$  cutting it off and allowing  
 plate voltage to rise. This rising grid voltage  
 is applied directly to the grid of  $\frac{1}{2}$  of  
 $V_4$ . This tube triode has a large amount  
 of feedback from plate ~~to grid through  $C_6 + R_{14}$~~   
~~sustained oscillation~~. The resulting  
 linearly increasing voltage is fed coupled  
 to a horizontal deflection plate of ~~311~~  $V_6$ .

thru  $C_{16}$  and a portion is applied to the grid of the other triode of  $V_4$  which is a paraphase inverter. This tube inverts the sawtooth which is now applied to the other pt deflection plate of  $V_6$  thru  $C_{16}$ .

The circuitry is simple and straightforward. There is room for improvement in layout especially high voltage components. To set this circuit up a scope such as with excellent high frequency response ~~should~~ <sup>must</sup> be used. Coupler A T.S. 239 should be adequate. Through a high impedance probe couple the plate of  $V_1$  to the scope and apply a negative trigger of about 25 volts to 1302 - this trigger can should be the trigger pulse of a G-30 but may be synthetic. Adjust  $R_7$  until the pulse form is locked in with the trigger. This can be determined by removing the trigger which should stop the pulse. Too high a setting

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of this control will result in inability to trigger the circuit while to low a setting will cause the circuit to run free without triggering. Correct setting is between these points  $\frac{1}{2}$  way

Q. Next move the probe to plate of  $V_3$  where a square pulse will appear. Width of this pulse controls width of range displayed on the A scope. Scale factor is  $490^{\prime \prime}/\mu\text{sec}$ .  $C_4$  should be adjusted until desired range is obtained. Settings of 5 to 7 micro seconds are normal.

Next display positive sweep on the scope by going ~~Q~~ to pin 5 of  $V_4$ .  $C_6$  must be adjusted for proper sweep rate. Too fast a rate will result in a rise to a sawtooth rising to a maximum and becoming flat for the remainder of the pulse while to slow a rate will mean a decreased amplitude. Correct setting is just beyond the point where flatness ends and where decreased amplitude is noticeable.

With a little experience all of these adjustments may be made by merely watching A scope presentation.

The G-30 is strictly stock with only tubes V

being removed to decrease power drain. T.O.s apply completely except to the range and other circuits disabled by removal of tubes.

~~There is one other exception when the~~

Cable diagrams for this installation are given in Diagram # [ 12 + 13 ]

Primary power wiring in plane and tank are given in Diagram # [ 10 ]

In order to eliminate any possibility of interference ~~with~~ primary of the magnetron H.V. supply is connected only ~~long~~ a few seconds before and during firing. Power for the scope power supply

is taken from any convenient point  
on the 115 V 400 W supply through  
a 1 amp fuse. This is not shown  
on these diagrams. Ships wiring is  
given in Drag. 11. A single point push  
to make ~~not~~ switch is placed in the  
tank for convenience in flight. This  
operates camera and radar.

To prevent overloads on G-30 component  
since additional filament and plate power  
is drawn from it tubes ~~# 1 -~~ <sup>tubes in the range</sup>  
~~computer section which are not used in this circuit should be removed.~~  
~~and removed. Other than this it is unmodified.~~  
① Set A.G.C. threshold until A.G.C. volt is  
-1. If gain is insufficient this may be  
reduced. D or ~~Not~~ Not connect the trigger  
cable from R.I. unit to ~~the~~ Range Computer,  
as this will operate a sinking circuit  
that obscures the ~~first~~ first portion of the  
trace.

Construction and mounting details are given in Drsg. # 1, 2, 3, 4, 5 & 6. These are detailed enough to be self explanatory.  
P This report was <sup>hurriedly</sup> assembled - and there are undoubtably ~~a~~ blank areas however we have readily available any additional information necessary.

as a method suitable for field use

proves the feasibility of this system. A ~~complete~~ complete system including radar, cameras, and A scopes at the R.T. unit of a G-30 was housed in a 120 gal M-116 napalm tank along with an A scope presentation which was photographed by a camera whose shutter openings were synchronized with those of another ~~35 mm~~ <sup>strike</sup> camera which served as a ~~strike~~ <sup>camera</sup>.

equipped with a 4" lens. This unit was ~~suspended~~ suspended from an 86 F. hurriedly assembled and without preliminary tests taken to Yuma T.T.B. where ~~intensive~~ <sup>3</sup> ~~intensive~~ <sup>chased by the 86</sup> rocket a large number of firings were being made. During the week ~~there~~ <sup>3</sup> successful firings were made with all 8 being successfully recorded.

This instrumentation in spite of its hurried design and construction and unnecessary complexity performed & required no maintenance.

~~Results were all~~ Results were extremely gratifying. Several hits were recorded which thus affording a check against instrumentation accuracy which proved to be excellent. This was the first instance of a firing error indicator functioning successfully in the field. Several conferences were held with ~~people~~ members of Air Defense and Training Commands as to the most ~~useful~~ satisfactory configuration of this system and it was decided that a chase plane equipped with this F.B.D. offered more advantages ~~primarily~~ than any others.

A unit was then designed using <sup>simply</sup> ~~with one exception,~~ stock A.T. items which is simple enough to be reproduced by any well equipped Air Force installation with machine shops and facilities

This scoring method is extremely versatile requiring basically only two sources of data, radar video information and photographic data from a strike camera.

We have built a series of these ~~systems~~ Radar-Optic ~~systems~~ F.E.I.s here using various configurations. They have fallen into roughly two classes. ~~Two units~~ systems mounted on the firing craft and using system's radar for video and those mounted on a chase plane with its own radar. The system described ~~the sys~~

described described in the following is the Model 26 which was designed for field use. It consists of an unmodified A-30 radar feeding a 4 tube sweep and wide chassis which whose output is

M-26

an 'A' presentation on a 35P11 cathode ray tube. A modified lens combines the image along one edge of the 35 mm film ~~along~~ with strike ~~on~~ photographs. A 40 f.p.s frames per second camera is used. Housing for the unit is ~~an~~ M-116 napalm tank with necessary changes ~~to~~. Weight is approximately 12.5 pound and drag is only slightly higher than a normal tank. The chase plane flies a fairly tight formation with firing craft and during the last two seconds few seconds ~~as~~ of a firing run radar ~~and~~ and camera are turned on for ten or 15 seconds.

\* ~~the~~ Voltage is ~~only~~ applied to the magnetron <sup>only</sup> during ~~the~~ this period to eliminate possibility of interference

for maintaining an 'E' system. A prototype of the unit was assembled and tested here and will be given to Yuma for further tests. This complete construction and operation of this unit<sup>details of F.E.I.</sup> are given in the attached appendix.

Since the concept of tracking ~~and~~ missiles with pulsed radar is relatively new and ~~it~~ opens a realm of possibilities in the missile field in general its specific application to as a practical T.O.D. ~~system~~<sup>for E system scoring</sup> will be described in detail. Restating the problem of photographic scoring: Ranging of missiles ~~from missiles~~ miss of rockets miss by motion picture photography is easily accomplished by stadiometric technique if the correct ~~a~~ and only if a rocket is in or near a <sup>perpendicular</sup> plane normal to the longitudinal axis of the strike camera ie a plane ~~through~~ through the target

Inser + P.  
a Ra  
g r a Ph  
o n M.  
b

parallel to the camera's film plane. ~~Accuracy~~  
 First order accuracies are determined solely by  
 the ~~correctness~~ errors in detecting the cutting  
 of target plane by ~~the~~ rockets and relation  
 of this to the strike camera film. Positional  
 errors thus become a function of time errors as  
 the target is in continuous, ~~on~~ linear motion.  
~~single~~ An example will illustrate. Assume that the  
 strike rocket ~~over~~ ~~crosses~~ <sup>where</sup> of a pattern crosses  
 the a target plane at some given time ~~missing~~  
 the target aim point by ~~by~~ 50 ft ~~left~~ lead  
 in azimuth. Suppose that a photograph  
 is taken ~~some~~  $\frac{1}{20}$  of a second later and  
~~miss distance is assumed~~  
~~data is taken~~ from this photograph. Errors  
 in azimuth will now vary directly as ~~the~~  
 speed of the target speed. Elevation errors  
 elevation errors are negligible since target  
 velocity is zero and vertical rocket velocity  
 arises only from gravity acceleration

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which is on the order of  $70 \frac{\text{ft}}{\text{sec}}$ . Errors in azimuth will now vary directly as target speed. In this case the with target will will have the missile will appear to have passed closer to the target by distance the target travel in  $\frac{1}{20}$  sec. With a target speed of  $300 \frac{\text{ft}}{\text{sec}}$  this error in azimuth would be 15' against an elevation error of 3.5'. It is obvious that the relation

Error in ~~distance~~ assessing target velocity (error miss distance in azimuth (ft)  $\frac{\text{ft/sec}}{\text{sec}}$ )

in determining time of crossing rocket plane (sec)

holds for this specific case.

Other errors are present in ranging technique but this time function error predominates. This of course leads to a more fundamental problem. Since rockets are fired during a relatively long period of

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\* should be footnoted \* .084 sec.  
time<sup>3</sup> approximately 1.25 secs for 890, ~~for~~ for 860  
and .168 sec for ~~for full salvos~~) ~~so~~

the rocket pairs must be followed separately  
and the time of crossing crossover time ~~is~~  
recorded ~~under~~ for each pair or one rocket  
must be chosen and the time of only this  
pair's crossover be recorded. The first procedure  
is ~~for~~ necessary for extremely accurate work  
in engineering tests. For evaluation of system  
accuracy it is enough to know where the so  
called strike rocket or pattern centroid for  
it is this rocket which is theoretically designed  
to hit target ~~onto~~ target aim point. Since  
neither missiles or ~~syst~~ fire control system  
is perfect it is necessary to add rockets  
before and after the strike rockets  
to bring kill probability to a reasonable  
figure. It is ~~so~~ the centroid which is  
scored with the system being described

\*

32 by interpolation

although it is possible to score other rocketts.

~~Since~~ Since time ~~of~~ Radar ~~is~~ without

sets used to determine range coincidence

~~Lanc~~ is ~~any~~ ~~G-30~~ AN/APG-30, on  
low power,

airborne, X band set with 5 KW peak &

commonly used for range data on A series  
sights.

It would be desirable to have a  
set with more power or at least an antenna  
of smaller beam angle but this is more

than offset by such factors as small size,  
light weight, simplicity and ease of maintenance.

Range information is displayed on a 3"

scope in an 'A' presentation. In this

coincident with transmitter output pulse  
presentation the beam is started at one

edge of the tube and is swept linearly

along ~~X axis~~

across the face of the screen. If return pulse

information is displayed along ~~X axis~~ the

resulting ~~set time in range scale giving~~  
~~range~~ on which ~~range of objects~~ distance  
of objects from the set may be determined.  
~~Absolute range is~~ Relative not absolute range  
is of primary interest here.

Since extremely short ranges are ~~not~~  
~~of~~ necessary here some complications  
arise since the sets are designed for much  
longer ranges. Radar range factor is  
approximately 490 per micro sec ~~with~~  
thus the .4 microsec pulse of ~~a~~ <sup>this</sup>  
I-30 covers 196 feet in space ~~if~~ Objects  
closer together than this cannot be separated  
on ~~a~~ presentation. Ideally the pulse length  
would approach zero with position of  
each scanned ~~an~~ object appearing as a single narrow line.  
Unfortunately practical limitations prevent this.  
~~so that~~ Rockets or salvo of rockets  
appears as a single pulse lengthened pulse

and the target as another relatively wide pulse.

After a little experience ~~pulse can time of~~  
~~for the centroid by injection~~  
 crossovers can be determined to within  
 one frame of film run at 40 frames per  
 sec even though the pulse width occupies  
 a relatively large amount of trace width.

~~Once correct azimuth time~~ At forty frames per second  
 the maximum error is less than  $\frac{1}{40}$  second ~~at~~ X  
 tow speed. At present speeds this is on the  
 order of 7 feet. Elevation error  $\epsilon_2$  is negligible  
 Once the ~~instant~~ of crossover of the  
 centroid is found it is only necessary to select  
 the centroid and of the pattern from strike  
 photographs and determine magnitude of  
 miss ~~from~~ stadiometrically. For use with  
 present targets a slide projector would be  
 desirable but not necessary. Experience here  
 has shown that pattern centroid is extremely  
 close to the center of a circle which encloses

all but obviously wild rockets. Choosing this point becomes simple after comparing observing several strike films. Once this point is chosen magnitude of miss is determined by comparison of ~~opp~~  
~~it is only necessary to compare to its distance~~  
~~from aim point with target length to determine~~  
~~image miss distance to image distance of centroid from~~  
~~magnitude of miss. aim point to image distance of target.~~

~~Adva-~~ This system approximates has much to recommend it. Indeed it is difficult to conceive of another system with the advantages of no target limitations, ~~at~~ ~~as~~ simple data reduction, and a record, photographic record of the firing passes realistic enough to evaluate offer incentive to a pilot to study his performance. To accurately evaluate a pass with any form of FET it is necessary to have a record of pilot's performance to determine errors introduced from steering.

~~Adva-~~ As mentioned before ~~the~~ ~~opp~~  
~~\* aim point on a non-reflective bounces with~~  
~~corner reflectors attached is of course the reflectors.~~  
~~It will vary with reflective targets.~~

the use of radar to obtain range data from missiles has many applications. It should be an extremely valuable tool in ballistics studies of velocity, acceleration, and pair dispersion. As an F.S.I. system its value is obvious. Many possibilities exist for its immediate utilization. ~~most~~  
~~the ready way~~ There is no reason why the Model 26 F.S.I. as described in the appendix should not be immediately reproduced for use at bases where firing programs are being conducted. At present it seems impractical to equip individual fighters with this system even though it would involve only a simple 'black box' and a camera. Such an installation would be far simpler than the Radar equipment which is presently being and scheduled for installation. It would be of vastly more use. The value of

an F.C.D. system needs no justification.

The development of this system should have far reaching effects on targets. Now instead of having to use banners as a crude attempt at scoring, the only function <sup>of a target</sup> need be provision of a radar target with realistic performance. A logical target configuration would be a radar reflector enclosed in a streamlined structure offering small drag. Once drag is reduced to a low figure it is possible to reduce cable size weight and drag as well as reduce tow reels & size weight and complexity. With this reduction in size weight and drag the next logical step is use of fighter craft of all to obtain realistic performance. Work has been done toward developing small low drag targets <sup>radar reflective</sup>.

by at least two companies one of targets  
has the added feature of frangibility  
which should be extremely attractive for  
streaming use. A prototype of a high speed  
target was recently constructed and preliminary tests of it  
are under way. Drag of such targets  
are approximately 50 lbs at  
300 knots T.A.S. Weight while weight is  
20 lbs. or less. Radar reflector area is  
equivalent to a <sup>3' diameter</sup> conventional round reflector.  
There are commercially available fishing  
lines which have adequate strength to tow  
these targets. With small cable, reel sizes  
can be cut to reasonable figures. It  
is a relatively minor problem to design  
a reel such that it could be carried under  
the wing of a fighter in a nacelle which

could also partially house the target  
for takeoff - Probably most practical  
of all would be a system target and  
small reel which could be attached  
to a conventional ~~sack~~ bomb or tank  
<sup>of a fighter</sup> sack ~~and~~ Once airborne the target could  
be released and after completion of  
mission both target and cable be  
detached from aircraft. This is an  
entirely feasible system even from an  
economic standpoint since cable and  
target should cost less than \$50. At present  
a marquisette target ~~costs~~ and reflector  
costs almost \$300. Seven of the smaller  
targets <sup>discarded after every mission</sup> would provide much longer time  
in the air than a single banner, and at  
these targets would ~~also~~ provide performance  
performance which banners never can.

If cost of maintenance of a present bomber type tow plane were compared to those of a fighter using small targets, target price becomes insignificant. Fighter type tow craft would provide ~~sqm~~ individual squadron with presently lacking tow facilities. There are many squadrons which if tow facilities were provided could carry out on firing programs rather than endlessly ~~do~~ shadow boxing, which is the extent what at the present training amounts to.

~~the~~ The radar optic scoring system described is a presently available ~~not~~ for immediate application to ~~the~~ scoring of 'E' systems equipped interceptors. New methods are involved but it but this is necessary if we are to

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close the ten year lag that presently exists in  
two target facilities. Even though ~~this system~~  
~~is at present~~ the importance of a  
~~satisfactory~~